MT1.1 (45 Points) Consider the following vectors in \mathbb{R}^3 :

$$oldsymbol{v}_1 = egin{bmatrix} 1 \ 1 \ 1 \end{bmatrix}, \quad oldsymbol{v}_2 = egin{bmatrix} 1 \ -1/2 \ -1/2 \end{bmatrix}, \quad ext{and} \quad oldsymbol{v}_3 = egin{bmatrix} 0 \ \sqrt{3}/2 \ -\sqrt{3}/2 \end{bmatrix}.$$

(a) (5 Points) Determine $\theta_{12} = \angle(v_1, v_2)$, the angle between vectors v_1 and v_2 . Solution: $\theta_{12} = \frac{\pi}{2}$

(b) (5 Points) Determine $\mu_{v_3} = \text{avg}(v_3)$, the mean of vector v_3 .

Recall: The mean of a vector $y \in \mathbb{R}^m$ is the arithmetic average of its components—namely,

$$\mu_y = \mathsf{avg}(oldsymbol{y}) = rac{y_1 + \dots + y_m}{m} = rac{1}{m} oldsymbol{y}^\mathsf{T} \, oldsymbol{1}.$$

Solution: $\mu_{v_3} = 0$

(c) (5 Points) Determine $\langle \boldsymbol{v}_2, \boldsymbol{v}_3 \rangle$, the inner product of vectors \boldsymbol{v}_2 and \boldsymbol{v}_3 . Solution: $\langle \boldsymbol{v}_2, \boldsymbol{v}_3 \rangle = 0$

(d) (10 Points) Explain why the set of vectors $\{v_1, v_2, v_3\}$ forms a basis in \mathbb{R}^3 . Solution: Show that the set is linearly independent and why the set must span \mathbb{R}^3 or show that the set are orthogonal and explain why this must mean the vectors form a basis.

(e) (20 Points) Consider the vector

$$m{x} = \left[egin{array}{c} 1/2 \\ -1 \\ 1/2 \end{array}
ight].$$

(i) (15 Points) Express x as a linear combination of the vectors v_1 , v_2 , and v_3 . That is, determine the coefficients α_1 , α_2 , and α_3 in the expansion

$$\boldsymbol{x} = \alpha_1 \boldsymbol{v}_1 + \alpha_2 \boldsymbol{v}_2 + \alpha_3 \boldsymbol{v}_3.$$

Solution:

$$\alpha_1 = 0$$

$$\alpha_2 = \frac{1}{2}$$

$$\alpha_3 = -\frac{\sqrt{3}}{2}$$

(ii) (5 Points) Are the values of α_1 , α_2 , and α_3 that you found unique? If so, explain why. If not, provide another set of coefficients β_1 , β_2 , and β_3 such that

$$\boldsymbol{x} = \beta_1 \boldsymbol{v}_1 + \beta_2 \boldsymbol{v}_2 + \beta_3 \boldsymbol{v}_3,$$

where $\beta_k \neq \alpha_k$ for at least some $k \in \{1, 2, 3\}$.

Solution: Yes, the α_1 , α_2 , and α_3 are unique.

MT1.2 (45 Points)

Let $\mathcal{P}_n = \operatorname{span}(1, t, \dots, t^n)$ denote a real-valued vector space of polynomials of degree less than, or equal to, n, where n is a nonnegative integer and $t \in \mathbb{R}$. A generic polynomial in \mathcal{P}_n can be expressed as follows:

$$p(t) = \sum_{i=0}^{n} p_i t^i = \underbrace{\begin{bmatrix} 1 & t & \cdots & t^n \end{bmatrix}}_{\boldsymbol{f}^\mathsf{T}(t)} \underbrace{\begin{bmatrix} p_0 \\ p_1 \\ \vdots \\ p_n \end{bmatrix}}_{\boldsymbol{p}} = \boldsymbol{f}^\mathsf{T}(t) \boldsymbol{p},$$

where $f(t) \in \mathbb{R}^{n+1}$ denotes the vector of monomials (you can think of it as a vector-valued function of t), $p \in \mathbb{R}^{n+1}$ denotes the vector of the coefficients, and T denotes transpose.

- (a) (5 Points) Determine dim \mathcal{P}_n , the dimension of the vector space \mathcal{P}_n . **Solution:** dim $\mathcal{P}_n = n + 1$
- (b) (26 Points) Define $\mathcal{V}\subseteq\mathcal{P}_n$ as the subset of all polynomials in \mathcal{P}_n that have t=0 as a root. That is,

$$\mathcal{V} = \left\{ p(t) = \sum_{i=0}^{n} p_i t^i \middle| p(0) = 0, p_i \in \mathbb{R}, i = 0, \dots, n \right\}.$$

- (i) (12 Points) Explain why V is a subspace of P_n . Solution: Show that V fulfills the 3 subspace properties.
- (ii) (10 Points) Determine a basis for V. **Solution:** $v_1(t) = t$, $v_2(t) = t^2$, ..., $v_n(t) = t^n$
- (iii) (4 Points) Determine $\dim \mathcal{V}$, the dimension of \mathcal{V} .

Explain your answer in a brief, yet clear and convincing manner.

You should be able to solve this part *even if* you're unsure of your solution to part (ii).

Solution: dim $\mathcal{V} = n$

(c) (14 Points) Define $W \subseteq \mathcal{P}_n$ as the subset of all polynomials in \mathcal{P}_n that have t=1 as a root. That is,

$$W = \left\{ p(t) = \sum_{i=0}^{n} p_i t^i \middle| p(1) = 0, p_i \in \mathbb{R}, i = 0, \dots, n \right\}.$$

(i) (4 Points) Determine $\dim \mathcal{W}$, the dimension of \mathcal{W} .

Solution: dim W = n

(ii) (10 Points) Determine a basis for W. Explain your answer in a brief, yet clear and convincing manner.

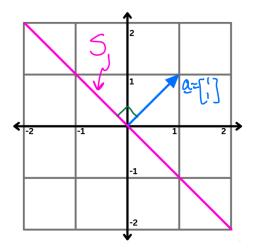
Solution: One possible basis is $w_1(t) = t - 1$, $w_2(t) = t^2 - 1$, ..., $w_k(t) = t^k - 1$.

MT1.3 (40 Points) Consider the vector $\boldsymbol{a} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ in \mathbb{R}^2 .

(a) (25 Points) Let's look at the subset S of \mathbb{R}^2 defined by

$$\mathsf{S} = \left\{ oldsymbol{x} \in \mathbb{R}^2 \middle| \left\langle oldsymbol{a}, oldsymbol{x}
ight
angle = 0
ight\}.$$

- (i) (5 Points) Describe, in simple words, the vectors x that form the set S. **Solution:** S consists of the set of points in \mathbb{R}^2 that are orthogonal to the vector a.
- (ii) (10 Points) Provide a single, well-labeled plot of the vector a and the set S in \mathbb{R}^2 . Use the standard orthogonal coordinate axes in \mathbb{R}^2 . Solution:



(iii) (10 Points) Is S a subspace of \mathbb{R}^2 ?

If you claim that S is a subspace, prove it.

If you claim that S is <u>not</u> a subspace, show that it fails at least one property of a subspace.

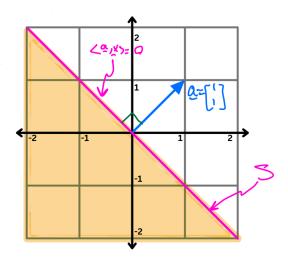
Solution: Yes, S is a subspace of \mathbb{R}^2 .

(b) (15 Points) Now let's look at the subset V of \mathbb{R}^2 defined by

$$\mathsf{V} = \left\{ oldsymbol{x} \in \mathbb{R}^2 \middle| oldsymbol{a}^\mathsf{T} oldsymbol{x} \leq 0
ight\}.$$

(i) (5 Points) On a well-labeled plot—using the standard orthogonal coordinate axes in \mathbb{R}^2 —shade the area corresponding to V.

Solution:



(ii) (10 Points) Is V a subspace of \mathbb{R}^2 ?

If you claim that V is a subspace, prove it.

If you claim that V is <u>not</u> a subspace, show that it fails at least one property of a subspace.

Solution: V is <u>not</u> a subspace.

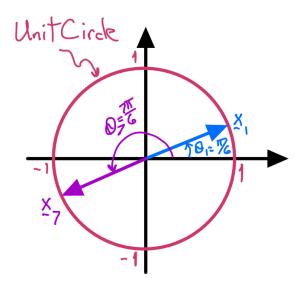
MT1.4 (35 Points) Consider the following set of twelve vectors in \mathbb{R}^2 :

$$\boldsymbol{x}_k = \begin{bmatrix} \cos\left(\frac{\pi}{6}k\right) \\ \sin\left(\frac{\pi}{6}k\right) \end{bmatrix}, \quad \text{for} \quad k = 0, 1, \dots, 11.$$

In what follows, you may or may not find it useful to know that

$$\cos\left(\frac{\pi}{6}\right) = \frac{\sqrt{3}}{2}$$
$$\sin\left(\frac{\pi}{6}\right) = \frac{1}{2}$$
$$\cos^2\alpha + \sin^2\alpha = 1$$
$$\cos\left(\pi + \alpha\right) = -\cos\alpha$$
$$\sin\left(\pi + \alpha\right) = -\sin\alpha.$$

- (a) (10 Points) Determine $||x_k||$, the Euclidean norm (i.e., 2-norm) of x_k . Does your expression depend on k? Explain why. **Solution:** $||x_k||^2 = 1$. This value does not depend on k
- (b) (10 Points) Draw each of the two vectors x_1 and x_7 on the same coordinate plane defined by the two standard orthogonal axes. Solution:



(c) (15 Points) Determine the vector

$$oldsymbol{v} = \sum_{\substack{k=0\k
eq 6}}^{11} oldsymbol{x}_k.$$

Your expression for \boldsymbol{v} must be in closed form—not, for example, in terms of a sum.

Hint: First determine the vector

$$oldsymbol{w} = \sum_{k=0}^{11} oldsymbol{x}_k,$$

and then infer the vector v from w.

Solution:
$$v = \sum_{k=0, k\neq 6}^{11} x_k = x_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

MT1.5 (20 Points) Consider the following two vectors in $\mathbb{R}^2_{>0}$:

$$oldsymbol{v} = egin{bmatrix} x \ y \end{bmatrix} \qquad oldsymbol{w} = egin{bmatrix} y \ x \end{bmatrix}.$$

We denote by $\mathbb{R}_{\geq 0}$ the set of all nonnegative real numbers—that is,

$$\mathbb{R}_{\geq 0} = \{ x \in \mathbb{R} | x \geq 0 \}.$$

And we denote by $\mathbb{R}^2_{\geq 0}$ the set of all vectors in \mathbb{R}^2 that have nonnegative components.

Accordingly, $x \ge 0$ and $y \ge 0$ above.

(a) (15 Points) Show that

$$xy \le \frac{x^2 + y^2}{2}.$$

Hint: Study the inner product $\langle v, w \rangle$ and make judicious use of the Cauchy-Schwarz Inequality.

Solution: Apply the Cauchy Schwarz inequality to v, w and expand the equation.

(b) (5 Points) Show that for any $a,b\geq 0$, the following inequality holds:

$$\sqrt{ab} \le \frac{a+b}{2}.$$

Solution: Use the equation from part a. Notice that this equation is very similar that one. How you can convert that inequality to this one?